Student-Run Autonomous Vessel for Oceanographic Research

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Outline

- Autonomous Vessels
- Our project
 - History
 - Mission
 - Design
 - Operation
- Results
 - Typical Data
 - Operational lessons
- Future plans and needs
- Video
- Questions and discussion





Autonomous Vessels

- Autonomous systems (drones)
 - Dirty
 - Dangerous
 - Dull
- Different from remotely piloted
- Many examples of small vessels
- Active research field
- Autopilots found on most crewed vessels both commercial and private





Images:

www.saildrone.com www.autonautusv.com www.whoi.edu yachtpals.com

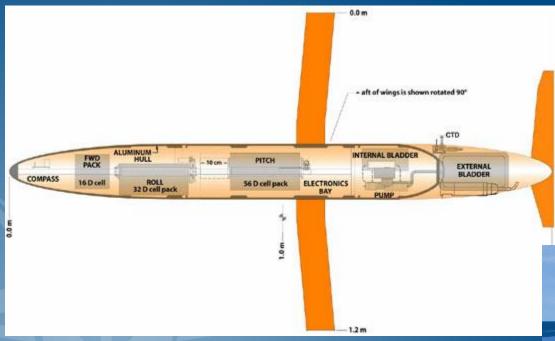


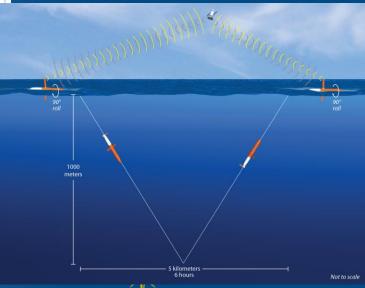
Sail Powered



http://abersailbot.co.uk/

Underwater





Surface Research Vessels



Autonomous Shipping

- Recent program at Rolls-Royce
- Norway has established a test zone (Trondheimsfjord)
- This scale brings up issues of economics and ethics along with the technological challenges.





Dumbo Mission

- Built and operated by students
 - Use off-the-shelf autopilot
 - Hobby grade hardware
- One hour voyages in Carquinez Strait
- Deliver accurate oceanographic measurements



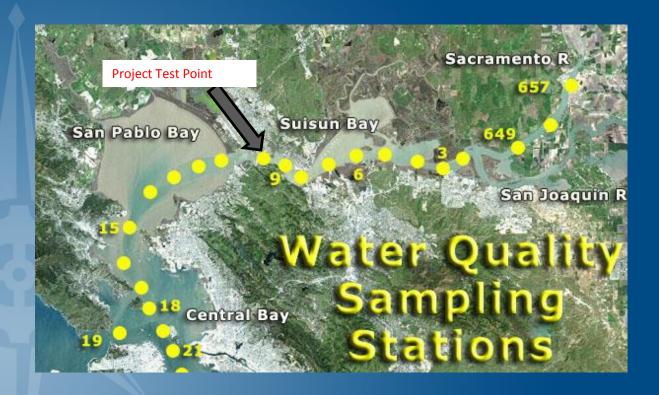


USGS Survey Vessel (Crewed)





Dumbo Mission Design Test Location

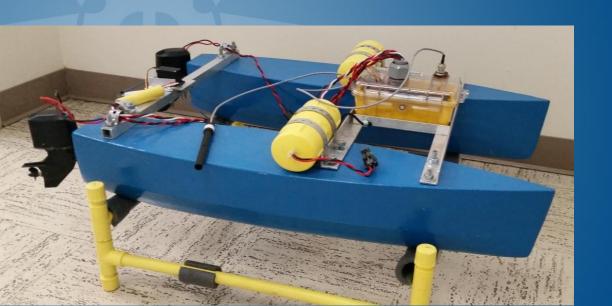


"Where Are Measurements Made? - USGS Water Quality of SF Bay." Where Are Measurements Made? - USGS Water Quality of SF Bay. N.p., n.d. Web. 08 Sept. 2016.



Dumbo History

- First version: Mechanical Engineering Capstone project
- Remotely piloted
- Solid foam hulls with externally mounted gear





History- Rose Hendrix

- 2014 COAST funding to add autonomous systems
- Existing hulls hollowed out to put systems inside



History- Jake Steiner

- 2015 COAST funding
 - new hulls
 - new propulsion
 - more sensors







Dumbo Construction- Student Built

- Wooden/fiberglass construction
- Hobby ROV thrusters
- APM open source autopilot system
- Payload system measures Temperature, Salinity, Dissolved Oxygen
- Measurements at specified waypoints
- Data is stored on SD card





APM (Ardupilot) Autopilot

- Multirotor drone guidance package: GPS, compass, attitude sensors, telemetry
- Ground vehicle firmware for boat
- Several control station options
- Open source hardware and software
- Documentation is disorganized, takes time to understand the complex system









Images:

http://ardupilot.org/



Dumbo limitations

- Only GPS/Compass sensor
 - No collision avoidance (operator responsibility)
 - No route checking (operator responsibility)
- A Captain is required for safe operation
- Configuration is sensitive to debris pickup
- Maintenance and reliability







Operations: Path Planning



Planned Path





Navigation Results



Oceanographic Measurements (Temperature)

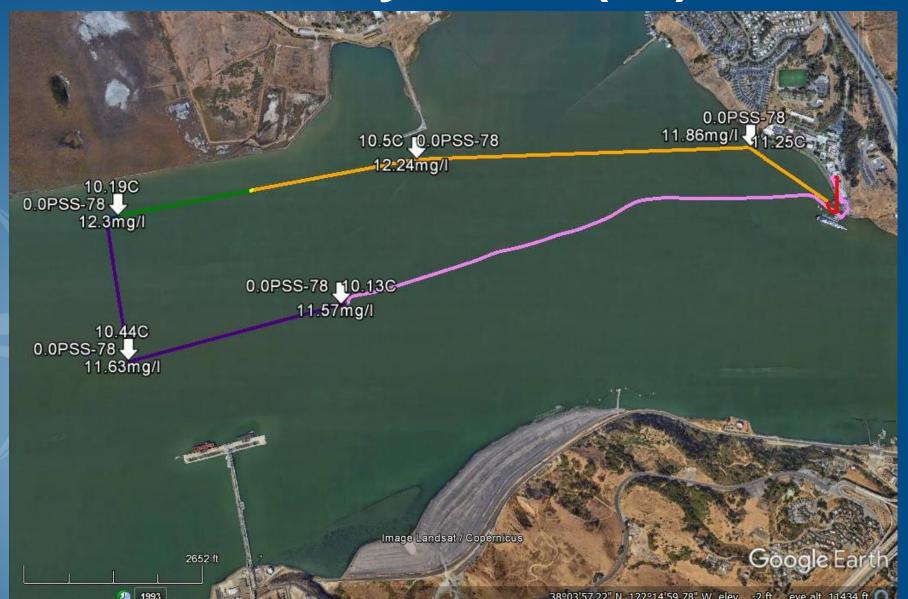


Isotherms



CAL MARITIME

USGS Survey Point (#9)

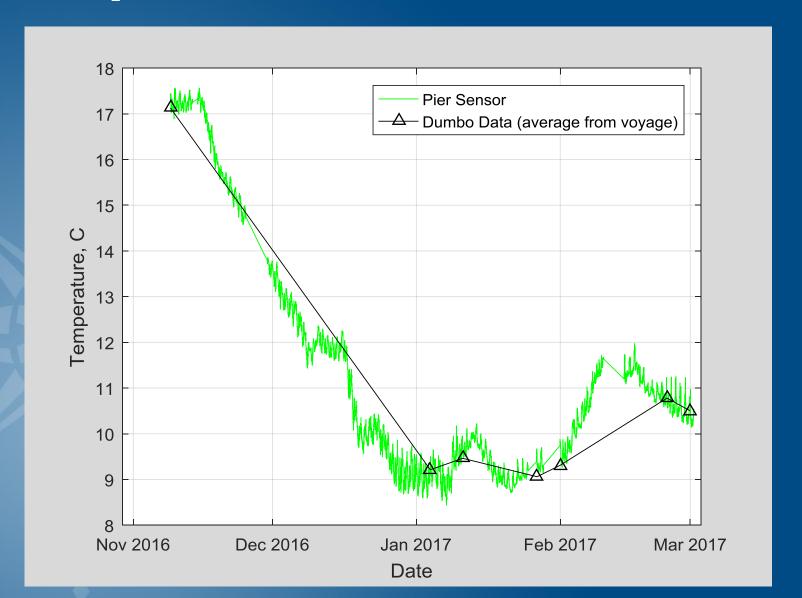


Operational Observations

- Aiming for weekly operations 2016-2017
- 10 runs in 18 weeks Nov-Feb
- Reliable Boat and Systems
- Operations canceled for:
 - Winter break
 - Busy students or faculty
 - Rain (operator preferenceboat is fine)
 - Debris fields



Temperature Data 2016-2017



Future Goals

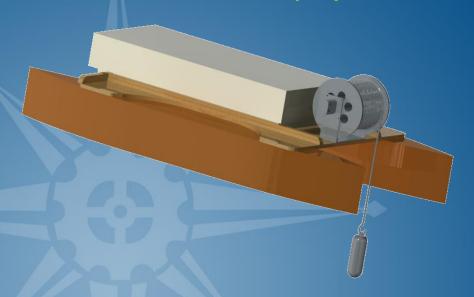
- Volunteers welcome: mholden@csum.edu
- Students to operate the boat regularly
 - Quality oceanographic observations for scientists
 - Record of operations/maintenance for engineers
 and economists





Future Work

- 2016-17 Capstone project
 - New sensor payload for measurements at depth





• Next boat: what is your mission?



Follow the voyage





Thanks

- Students
 - Rose Hendrix
 - Jake Steiner
 - Alec Safreno
 - Brian Haug
 - Jordan Escarcega
 - Brian Kuan
 - Kaelan Schorger

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 - Rich Muller
- Boathouse staff
 - Bob Brown
 - Leo Baclig
 - Jack Lavariega
 - Oleg Kilafly

